### FINAL REPORT

FOR THE MARINE SEISMIC SURVEY

OFFSHORE NOVA SCOTIA

AUGUST 8, 1988 TO AUGUST 31, 1988

FOR ATLANTIC GEOSCIENCE CENTER

GEOLOGICAL SURVEY OF CANADA

вч

WESTERN GEOPHYSICAL, A DIVISION OF
WESTERN ATLAS CANADA, Ltd.
M/V RESOLUTION
PARTY 115

## TABLE OF CONTENTS

Α.	INTRODUCTIONPage	1	-	2
в.	PROSPECT SUMMARYPage	3		
c.	CLIENT REPRESENTATIVES & WESTERN PERSONNEL Page	4		
D.	CHRONOLOGICAL EVENT SUMMARYPages	5	-	12
Ε.	FIELD ACQUISITION PARAMETERS			
	1. Energy SourcePage	13		19
	2. Cable ConfigurationPages	20	-	21
	3. Parameter & Equipment ReportPage	22		
	4. InstrumentsPage	23		
	5. Navigation ParametersPages	24	-	26
F.	WESTERN RESOLUTION EQUIPMENT LISTPages	27	-	3 (
G.	LRS-16A TECHNICAL SPECIFICATIONSPages	31	-	4 2
н.	WISDOM® SYSTEMPages	42	-	45
I.	EQUIPMENT TESTSPages	46		
J.	SURVEY PARAMETER AND LINE INFORMATION			
	1. Survey Definition			
	2. Survey Line InformationPages	47		
к.	SUMMARYPage	49		

## ILLUSTRATIONS

TIME ANALYSIS (FIGURE A)Page	12
GUN ARRAY GEOMETRY (FIGURE 1)	13
SYNTHETIC SIGNATURE (FIGURES 2, 3, AND 4)Pages	14 - 16
SOURCE ARRAY RESPONSE (FIGURE 5)Page	17
RECEIVER ARRAY RESPONSE (FIGURE 6)Page	18
SOURCE AND RECEIVER GEOMETRY (FIGURE 7)Page	19
6 HZ LOW CUT RESPONSE (FIGURE 8)Page	21
VESSEL REFERENCE OFFSET (FIGURE 9)Page	25
STREAMER CONFIGURATION (FIGURE 10)Page	42
WISDOM® INTERFACE (FIGURE 11)Page	43
SURVEY PARAMETERS AND MAP (FIGURE 12)Page	48

#### A. INTRODUCTION

Western Geophysical (a division of Western Atlas Canada Ltd.) was contracted to acquire 583 kilometers of deep seismic data for the Atlantic Geoscience Centre in two line segments offshore Nova Scotia, from August 8, 1988 to August The purpose of the survey was to uncover information about the earth's crust and in order to accomplish this end, long record lengths from 21 to 24 seconds were required, as well as a wide airgun array of large volume. The vessel used on this project was the M/V Resolution which is a state of the art diesel-electric powered seismic ship capable of dual streamer/dual array acquisition. This survey required only a single streamer and single source array and the recording system used was LRS-16A with a 4800m, 180 channel digital streamer. Where the currents were very strong near the Bay of Fundy, the streamer length was shortened to 3200m at 120 channels for greater control. The source was an LRS-7000, 1800 psi, 8100 cu.in. airgun array 76 meters wide. Navigation positioning was accomplished using the LORAN C system.

Several problems were encountered during the course of the survey. Two of the vessel's generators failed and repairs took 8 days in Halifax harbor. Recording time on the prospect was lost due to very strong currents which caused streamer imbalance and noise, and also due to very active fishing in some areas.

A field office was set up in Halifax, Nova Scotia for the duration of the survey with support coming from Western's Calgary office. All supplies and services were purchased in Halifax. These included customs agency services,

accommodation, shipping, food, fuel, and hardware.

Prior to operations, the vessel was inspected by Dr. Charlotte Keen of Atlantic Geoscience Centre.

#### B. PROSPECT SUMMARY

Number of Lines:
Shooting Interval:
Average Line Length:
(including taper)
Number of Survey Km:
(including taper)
Record Length:
Sample Rate:
Recording System:

2 80.00 / 53.34 meters 300 km

600 km

21 TO 24 sec. 4 msec. LRS-16A

#### 3. FIELD SYSTEMS -

a. Recording Vessel: M/V RESOLUTION

b. Energy Source:

8100 cubic inch low pressure airgun array comprised of 6 identical sub-arrays with 7 guns per sub-array.

c. Streamer and Cables:

120 Channel - 3200 meter Digital Streamer or 4800 meter Digital Streamer. The cable consisted of 120 or 180 groups each with a group interval of 26.67 meters.

d. SSTS:

High Resolution Acoustic trilateration system for near offset streamer positioning.

e. Recording System - LRS16A.

## C. CLIENT REPRESENTATIVES & WESTERN PERSONNEL

Client Representatives for Atlantic Geoscience Center

Bob Heins Geophysical Consultant

Key personnel to be engaged in the project are listed below:

Supervisor

Party Manager

Coodinator

Digital Technician(s)

Gun Operator(s)

Observers

Navigators

Compressor

Leo Snowman

Bo Wilkerson

Curtis Sims

Brandon Wells

Mark Sherry

John Reese

Todd Parish

Brandon Halbrook

Tony Jensould

Eric Foster

Ernie Renner

Cliff Hearn

James Wells

Ron gregory

Christopher Papadakis

Dan Zapada

Brian Moncado

Brennan Says

# D. CHRONOLOGICAL EVENT LOG

START END HOURS CODE LINE TIME TIME NAME	STATUS	FSP	LSP HDG	TOTAL	TOTAL KILOMETERS	TAPES REMARKS USED
** DATE: 08/06/88		0	0	0	0.0000	0 U/W TO NEXT PROSPECT
1420 2400 9.67 TT						_
** Subtotal ** 9.67				0	0.0000	0
7.07						
** DATE: 08/07/88						0 U/W TO PROSPECT
0 2400 24.00 TT		0	0	0	0.0000	0 0/4 10 11001011
** Subtotal **						0
24.00				0	0.0000	<b>U</b>
** DATE: 08/08/88					0.0000	0 U/W TO PROSPECT
0 2217 22.28 TT		0	0	0		RABSON, F. HALL AND
2217 2258 0.69 OT		0	0	0	0.0000	A. HAYES TO A SUPPLY BOAT
			_	0	0.0000	DDOCDECT
2258 2320 0.36 TT		0		0		CARLES CARLES
2320 2400 0.67 CI		0	0		, 0.000	
** Subtotal **				(	0.000	0
24.00				`		
** DATE: 08/09/88		(	n 0		0.000	0 0 LAYING CABLE 4800M
0 329 3.48 CI			0		0.000	O O U/W TO LINE
329 400 0.52 LC			0		0 0.000	0 0 WORKING ON LEAKAGE BIRD AND COMPASS
400 1030 6.50 CW		,				LINE
			0 0		0 0.000	0 CABLE OUT CHECKING OUT CABLE BALANCE
1030 1232 2.03 LC						PULLING AWAY FROM TRAWLERS O DICKING UP CABLE BALANCING CABLE
			0 0		0 0.000	
1232 1906 6.57 TR			0 0		0.000	
1906 2350 4.73 LC						LINE LAYING GUN
4.7 CV			0 0		0 0.00	00 0 ABORT LINE DUE TO GUNS TWO GUNS OUT
2350 2400 0.17 GN						
** Subtotal **					0 0.00	00 0
24.00						
** DATE: 08/10/88						00 0 CIRCLING DUE TO GUNS
0 150 1.83 GN			0 0		0 0.00	- room CHIDS DOWED
150 300 1.17 SR			0 0		0 0.00	DESCRIPTION AND CABLE ONLY TWO
300 630 3.50 CI			0 0		0 0.00	GENERATORS WORKING
300 030 2.30 02						- CONTING ON GENERATORS 1316-1518
630 2400 17.50 SR			0 0		0 0.00	MOVING CABLE OVER TO PORT REEL
030 2400 17.30 5						MOATING CURPER 2. THE TO THE PERSON OF THE P
** Subtotal **						000 0
24.00					0 0.0	000
****						

START END HOURS CODE LI	NE STATUS ME	FSP L	SP HDG TOTA SHOT		TOTAL TAPP OMETERS USE	
** DATE: 08/11/88		o	0 .	0	0.0000	0 TWO GENERATORS DOWN
24.00						
** DATE: 08/12/88 0 1757 17.95 SR		0	0	0	0.0000	0 TWO GENERATORS DOWN 0550-TWO MEN ON BOARD FOR GENERATORS
1757 2300 5.05 TT		0	0	0	0.0000	0 U/W TO HALIFAX FOR GENERATOR REPAIR 0 TIED TO DOCK- HALIFAX REPAIRING
2300 2400 1.00 SR		0	0	0	0.0000	0 TIED TO DOCK- HALIFAX REPAIRING GENERATORS
** Subtotal ** 24.00				0	0.0000	0
** DATE: 08/13/88 0 2400 24.00 SR ** Subtotal **		0	0	0	0.0000	O AT HALIFAX REPAIRING GENERATORS
24.00				0	0.0000	0
** DATE: 08/14/88 0 2400 24.00 SR		0	0	0	0.0000	O AT HALIFAX REPAIRING GENERATORS
** Subtotal ** 24.00				0	0.0000	0
** DATE: 08/15/88 0 2400 24.00 SR		0	0	0	0.0000	O AT HALIFAX REPAIRING GENERATORS
** Subtotal ** 24.00				0	0.0000	0
** DATE: 08/16/88 0 2400 24.00 SR		0	0	0	0.0000	O AT HALIFAX REPAIRING GENERATORS
** Subtotal ** 24.00				0	0.0000	0
** DATE: 08/17/88 0 2400 24.00 SR		0	0	0	0.0000	O AT HALIFAX REPAIRING GENERATORS
** Subtotal ** 24.00				0	0.0000	0
** DATE: 08/19/88 0 129 1.48 IN		0	0	0	0.0000	O CIRCLING FOR INSTRUMENT PROBLEMS
0 129 1.48 IN 129 140 0.19 PR	88-1 I	0	0 142	0	0.0000	1 SP101-120 NO GOOD DUE TO INSTRIMENT PROBLEMS
140 2220 20.66 IN		0	0	0	0.0000	0 PROBLEM WITH MOSTEK MEMORY 1901-1955 HELO ON BOARD LYLE GETTING OFF
2220 2400 1.67 PR	88-1 I	101	268 142	168	13.4400	1 SP 101-120 WERE A SHOTS 268 LAST SHOT OF THE DAY

START END TIME TIME	HOURS C		LINE NAME	STATUS	FSP	LSP E	EDG	TOTAL	TOTAL KILOMETERS		REMARKS
** Subtotal	**										
	24.00							168	13.4400	2	
** DATE: 08	/20/88							•			
	7.93 F	R	88-1	I	269	1102	142	834	66.7200	11	STOPPED DUE TO GUNS
756 1226	4.50 G	N		•	0	0		0	0.0000	-	CIRCLING FOR GUNS
1226 2243	10.29 E	PR.	88-1	С	1103	2122	142	1020	81.6000	11	SP1072-1102 A SHOT STOPPED LINE DUE TO LONGLINERS
2243 2400	1.28 F	7			0	0		0	0.0000	0	CIRCLING FOR FISHING GEAR
** Subtotal	**								*** 2000	22	
	24.00							1854	148.3200	22	
** DATE: 08	/21/88										
	7.40 (	CW			0	0		0	0.0000	0	WORKING ON NOISY GROUPS HAD CABLE PROBLEMS ON THE WAY BACK OUT
724 1022	2.97	F			0	0		0	0.0000	0	CABLE OUT U/W TO LINE OFFSET 26KM TO THE NE DUE TO FISHING GEAR
1022 1428	4 10 1	מס	88-1A	I	2062	2509	142	448	35.8400	5	STOPPED DUE TO GUNS
1428 1730			00 111	•	0	0		0	0.0000	0	CIRCLING DUE TO GUNS
1730 1836					0	0		0	0.0000	0	CIRCLE EXTENDED DUE TO SHIP TRAFFIC
1836 1930			88-1A	I	2508	2568	142	61	4.8800	1	SP2477-2507 WERE A SHOTS STOPPED DUE TO CABLE TRIM
1930 2400	4.50	TR			0	0		0	0.0000	G	1930-2039 PICKING UP GUNS 2039- START CABLE UP FOR CABLE TRIM
** Subtotal	**										
Subscoul	24.00							509	40.7200	6	
** DATE: 08	3/22/88										
0 20	5 2.08	TR			0	0		0	0.0000		BALANCING CABLE
205 330	1.42	LC			0	0		0	0.0000		CABLE OUT U/W TO LINE SP2518-2568 WERE A SHOTS STOPPED FOR
330 650	3.33	PR	88-1A	I	2569	2868	142	300	24.0000		SHIP NOISE
650 101	5 3.42	S			0	0		0	0.0000		CIRCLING FOR SHIP NOISE
1015 124	8 2.55	PR	88-1A	I	2808	3073	142	2 266	21.2800		S SP2808-2868 WERE A SHOTS STOPPED FOR LRS 100 PROBLEMS
1248 161	4 3.43	IN			0	0		0	0.0000		CIRCLING FOR LRS 100
1614 173	3 1.32	PR	88-1A	I	3085	3162	142	2 78	6.2400	) ;	2 SP3043-3084 WERE A SHOTS STOPPED FOR TIME BREAK PROBLEMS
1733 213	7 4.07	IN			0	0		0	0.0000	) (	CIRCLING FOR TIME BREAK PROBLEM LRS
2137 240	0 2.38	PR	88-1A	I	3163	3307	142	2 145	11.6000	)	4 SP3043-3084 B SHOTS SP3085-3162 A SHOTS LAST SHOT OF THE DAY
** Subtota	1 **										
	24.00							789	63.1200	) 1	3

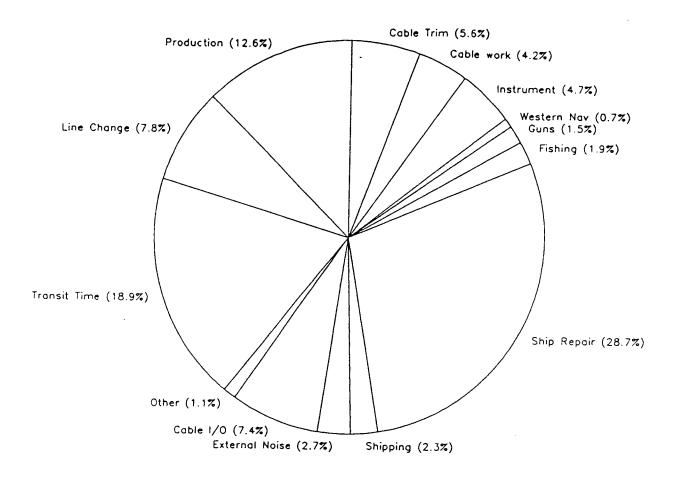
START END HO	OURS CODE		STATUS	FSP	LSP H	DG TOTA			TAPES REMARKS
TIME TIME		NAME				SHOT	rs i	KILOMETERS	OSED
** DATE: 08/23			_		0444			24 0400	4 STOPPED DUE TO CABLE TRIM
0 255 2		88-1A	I	3308	3644 1			26.9600 0.0000	0 PICKING UP BALANCING CABLE CABLE OUT
255 1217 9	9.36 IK			Ū	· ·	~	Ü	0,000	10:46 AND U/W TO LINE
1217 1626 4	4.15 PR	88-1A	I	3645	4122 1	42 47	78	38.2400	6 SP3600-3644 WERE A SHOTS STOPPED DUE TO NAV. (LORAN OUT OF SPEC.)
1626 2110 4	4.74 WN			0	0		0	0.0000	O CIRCLING FOR NAVIGATION
2110 2400 2	2.83 PR	88-1A	I	4123	4305 1	42 18	83	14.6400	4 SP4020-4122 WERE A SHOTS LAST SHOT OF THE DAY
** Subtotal **	*								
24	4.00					99	98	79.8400	14
** DATE: 08/24		88-1A	С	4306	4472 1	42 14	67	13.3600	3 LINE COMPLETED
0 135 1 135 353 2		00-IX	C	0	0	74 1	0	0.0000	O PICKING UP GUNS AND CABLE
353 2400 20				0	0		0	0.0000	0 CABLE ON BOARD U/W TO LINE 88-2
** Subtotal **									
24	4.00					10	67	13.3600	3
** DATE: 08/25				0	0		0	0.0000	0 U/W TO LINE 88-2
0 408 4 408 903 4				0	0		0	0.0000	0 LAYING CABLE TAKING OFF SOME WEIGHTS
903 1200				0	0		0	0.0000	O CABLE OUT CHECKING CABLE BALANCE
,,,,			•						LAYING GUNS
1200 1229	0.48 F			0	0		0	0.0000	O PICKING UP GUNS DUE TO LONGLINER GEAR
									ALL AROUND US
1229 1404	1.59 F			0	0		0	0.0000	0 PICKING UP CABLE LONGLINER GEAR ALL AROUND US 1 BIRD DAMAGED
1404 1555	1 85 F			0	0		0	0.0000	O RUNNING LINE TO FIND THE END OF FISHING
1404 1555	1.05 1			ŭ	·		•	.,	GEAR
1555 2104	5.15 CI			0	0		0	0.0000	O LAYING CABLE REPAIRING SOME SECTIONS
									WITH HOLES
2104 2220	1.26 LC			0	0		0	0.0000	O CABLE OUT CHECKING CABLE BALANCE
2220 2400				0	0		0	0.0000	0 PICKING UP CABLE SECTION 29B BAD
0 408				0	0		0	0.0000	0 U/W TO LINE 88-2 0 LAYING CABLE TAKING OFF SOME WEIGHTS
408 903				0	0		0	0.0000	O CABLE OUT CHECKING CABLE BALANCE
903 1200	2.95 LC			U	U		U	0.0000	LAYING GUNS
1200 1229	0.48 F			0	0		0	0.0000	O PICKING UP GUNS DUE TO LONGLINER GEAR ALL AROUND US
1229 1404	1.59 F			0	0		0	0.0000	0 PICKING UP CABLE LONGLINER GEAR ALL AROUND US 1 BIRD DAMAGED
1404 1555	1.85 F			0	0		0	0.0000	O RUNNING LINE TO FIND THE END OF FISHING GEAR
1555 2104	5.15 CI			0	0		0	0.0000	0 LAYING CABLE REPAIRING SOME SECTIONS WITH HOLES

		HOURS	CODE		STATUS	FSP	LSP H	DG TOTAL	TOTAL	TAPES	REMARKS
TIME	TIME			NAME				SHOTS	KILOMETERS	USED	
2104	2220	1.26	LC			0	0	0	0.0000	0	CABLE OUT CHECKING CABLE BALANCE
2220	2400	1.67	CW			0	0	0	0.0000		PICKING UP CABLE SECTION 29B BAD
** Subt	total	**									
		48.00						0	0.0000	0	
** DATE			WD.								
		3.03 0.60		88-3A	I	0 166	0	0	0.0000		CIRCLING DUE TO CURRENTS
302	330	0.00	IX	00 JA	-	100	260 03	38 95	5.0667	1	STOPPED FOR CREW BOAT TO TRANSFER PEOPLE SP166-196 WERE A SHOTS
338	638	3.00	LC			0	0	0	0.0000	0	CIRCLING TO TRANSFER PERSONNEL
							•	•		•	0400-0410 TRANSFER PERSONNEL
638	752	1.24	LC			0	0	0	0.0000	0	EXTENDED FOR SATELLITE FIX
752	859	1.11	PR	88-3A	I	261	372 03	38 112	5.9741	2	SP230-260 WERE A SHOTS STOPPED FOR
											SHIP NOISE
		2.70				0	0	0	0.0000	0	CIRCLING FOR SHIP NOISE
		2.19			_	0	0	0	0.0000		CIRCLING AGAIN FOR SHIP NOISE
1352	1414	0.36	PR	88-3A	I	342	406 03	38 65	3.4671	1	SP342-372 WERE A SHOTS CABLE OUT OF SPEC. DUE TO CURRENTS
1414	1743	3.49	TR			0	0	0	0.0000	0	CIRCLING FOR CURRENTS
1743	1757	0.23	PR	88-3A	I	0	0 03	38 0	0.0000		SP342-372 B SHOTS STOPPED FOR CABLE OUT OF SPEC. DUE TO CURRENTS
1757	1830	0.55	EN			0	0	0	0.0000	0	CIRCLING FOR NOISE DUE TO CURRENTS
1830	2130	3.00	OT			0	0	0	0.0000		STANDING BY FOR CLIENT ON WHAT TO DO NEXT
2130	2400	2.50	LC			0	0	0	0.0000	0	U/W TO LINE 88-4
** Subt	otal	**									
		24.00						272	14.5079	5	
** DATE	: 08/	26/88									
		4.93				0	0	0	0.0000	0	CHANGING OUT SECTION 29B AND REPEATER
		2.69				0	0	0	0.0000	0	CABLE OUT U/W TO LINE
737	1155	4.30	CW			0	0	0	0.0000		ABORT LINE FOR NOISY SECTION PICKING UP GEAR WORKING ON CABLE
		3.38				0	0	0	0.0000	0	CABLE OUT U/W TO LINE
1518	1942	4.40	PR	88-2	I	310	722 34	8 413	33.0400		STOPPED DUE TO CABLE NOISE DUE TO CURRENTS
1942	2400	4.30	EN			0	0	0	0.0000		CIRCLING FOR NOISE FROM CURRENTS 2112-2241 REPLACED SYNTRIEVES M.O.B
** Subt	otal	**									
		24.00						413	33.0400	5	
** DATE	: 08/	27/88									
0	29	0.48	EN			0	0	0	0.0000	0	CIRCLING FOR NOISE FROM CURRENTS
29	41	0.20	PR	88-2	I	662	686 34	8 25	2.0000		SP662-686 WERE A SHOTS CURRENTS AFFECTING BALANCE AND NOISE

STADT	END	HOURS	CODE	LIME	C			_		
	TIME	HUUKS	CODE	NAME	STATUS	FSP	LSP HD	G TOTAL		TAPES REMARKS
11111	11111			IVALIE				SHOTS	KILOMETERS	USED
41	350	3.15	CI			0	0	0	0.0000	0 PICKING UP GUNS AND CABLE
350	804	4.24	TT			0	0	0	0.0000	
						•	Ū	· ·	0.0000	0 U/W TO LINE 88-3 0750-0804 TRANSFER
804	1020	2.26	CI			0	0	. 0	0.0000	CREW TO AND FROM LA CUNDA O LAYING CABLE OUT
1020	1303	2.72	LC			0	0	0	0.0000	
1303	1526	2.38	PR	88-3	I	101	376 03	_	22.0800	
1526	2100	5.57	CI			0	0	0	0.0000	3 STOPPED DUE TO NOISE FROM CURRENTS
						-	·	·	0.0000	0 PICKING UP GEAR CHANGING FROM 4800M TO 3200M CABLE
2100	2313	2.22	LC			0	0	0	0.0000	0 CABLE OUT U/W TO LINE
2313	2351	0.63	PR	88-3A	I	101	196 038	-	5.1206	1 STOPPED DUE TO CURRENTS
2351	2400	0.15	TR			0	0	0	0.0000	
** Subt	otal	**					•	·	0.0000	0 CIRCLING DUE TO STRONG CURRENTS
		24.00						397	29.2006	5
** DATE	: 08/	28/88								
0	302	3.03	TR			0	0	0	0.0000	0 CIRCLING DUE TO CURRENTS
302	338	0.60	PR :	88-3A	I	166	260 038	95	5.0667	1 STOPPED FOR CREW BOAT TO TRANSFER PEOPLE
										SP166-196 WERE A SHOTS
338	638	3.00 1	LC			0	0	0	0.0000	0 CIRCLING TO TRANSFER PERSONNEL
										0400-0410 TRANSFER PERSONNEL
638	752	1.24 1	LC			0	0	0	0.0000	0 EXTENDED FOR SATELLITE FIX
752	859	1.11 I	PR 8	38-3A	I	261	372 038	112	5.9741	2 SP230-260 WERE A SHOTS STOPPED FOR
										SHIP NOISE
859 1	1141	2.70 \$	3			0	0	0	0.0000	0 CIRCLING FOR SHIP NOISE
1141 1	1352	2.19 8	3			0	0	0	0.0000	O CIRCLING AGAIN FOR SHIP NOISE
1352	414	0.36 E	PR 8	38-3A	I	342	406 038	65	3.4671	1 SP342-372 WERE A SHOTS CABLE OUT OF
										SPEC. DUE TO CURRENTS
1414 1						0	0	0	0.0000	O CIRCLING FOR CURRENTS
1743 1	.757	0.23 F	PR 8	8-3A	I	0	0 038	0	0.0000	1 SP342-372 B SHOTS STOPPED FOR CABLE
										OUT OF SPEC. DUE TO CURRENTS
1757 1						0	0	0	0.0000	O CIRCLING FOR NOISE DUE TO CURRENTS
1830 2	130	3.00 O	T			0	0	0	0.0000	O STANDING BY FOR CLIENT ON WHAT TO DO
										NEXT
2130 2			C			0	0	0	0.0000	0 U/W TO LINE 88-4
** Subto										
	2	4.00						272	14.5079	5
++ DATE:	00.0	0 /00								
** DATE:			<b>a</b>							
		5.68 L		0 /	-	0	0	0	0.0000	0 U/W TO LINE 88-4
74 T T	114	6.19 P	r 8	8-4	I	101	870 315	770	41.0718	7 STOPPED DUE TO CURRENTS CABLE OUT OF
1159 1	400	ית כו ל	NT.							SPEC.
1152 1400 11						0	0	0	0.0000	O CIRCLING FOR NOISE DUE TO CURRENTS
1400 1.	درر	1.74 U.	1			0	0	0	0.0000	0 PICKING UP GEAR DANGER OF DAMAGING
1555 20	003	4 12 T	т			•		_		CABLE TO SHOOT MORE ON THIS LINE
2000 20	<del>-</del>		-			0	0	0	0.0000	0 CABLE ON BOARD U/W TO 88-2

START END	HOURS	CODE	LINE	STATUS	FSP	LSP HT	G TOTAL	TOTAL	TAPES	REMARKS
TIME TIME			NAME				SHOTS	KILOMETERS	USED	
2003 2203	2.00	CI			0	0	0	0.0000	0	LAYING CABLE
2203 2400	1.95	LC			0	0	0	0.0000	0	CABLE OUT U/W TO LINE
** Subtotal	**									
	24.00						770	41.0718	7	
** DATE: 08/										
	0.12				0	0	0	0.0000	0	U/W TO LINE
7 715			88-2A	I	101	1034 16	8 934	49.8196	8	STOPPED FOR NOISE DUE TO CURRENTS
715 1033					0	0	0	0.0000	0	CIRCLING FOR NOISE DUE TO CURRENTS
1033 1100	0.45	PR	88-2A	I	1004	1052 16	8 49	2.6137	1	SP1004-1034 A SHOTS STOPPED FOR NOISE DUE TO CURRENTS
1100 1401	3.02	EN			0	0	0	0.0000	0	CIRCLING FOR NOISE DUE TO CURRENTS
1401 1748	3.78	PR	88-2A	I	1022	1516 16	8 495	26.4033	4	SP1022-1034 B SHOTS SP1035-1052 A SHOTS
										STOPPED FOR NOISE
1748 2040	2.87	EN			0	0	0	0.0000	0	CIRCLING FOR NOISE DUE TO CURRENTS
2040 2400	3.33	PR	88-2A	I	1486	1971 16	8 486	25.9232	3	LAST SHOT OF THE DAY
** Subtotal	**									
	24.00						1964	104.7598	16	
** DATE: 08/	31/88									
0 24	0.40	PR	88-2A	С	1972	2030 16	8 59	3.1471	1	LINE COMPLETE
24 224	2.00	CI			0	0	0	0.0000	0	PICKING UP GUNS AND CABLE
224 2400	21.60	TT			0	0	0	0.0000	0	CABLE ON BOARD U/W TO HALIFAX
** Subtotal	**									
	24.00						59	3.1471	1	
*** Total **	*									
	633.7						8632	599.0351	104	

# TIME BREAK DOWN ( FIGURE A )



#### E. FIELD ACQUISITION PARAMETERS

TYPE WESTERN LOW PRESSURE AIR GUNS. NO. GUNS 42

ARRAY VOLUME 8100 CU.IN. GUN ARRAY DEPTH 10 MTR

SHOTPOINT INTERVAL 80.00 MTR AIR PRESSURE 1800 PSI

SPECIAL INSTRUCTIONS: <u>EACH SUBARRAY IS CONFIGURED THE SAME</u>
( FIGURE 1 ) ENERGY SOURCE CONFIGURATION

( FIGURE I ) ENERGI SOURCE CONFIGURATION

NAVAGATION REFERENCE POINT (NRP) IS LOCATED AT \_\_\_\_\_CABLE STERN ROLLER\_ (X)\_ STERN <-<u>12 MTR</u> ---->|<--<u>12</u>-->|<--<u>14</u>--->|<--<u>14</u>-->|<-<u>12</u>->|<-<u>12</u>-> 94 MTR 106 MTR 118 MTR (9) v (17)(25)(<u>33</u>) (<u>33</u>) (1) - -4.0 MTR (<u>2</u>)--(26)(34)(34)(10)(18)4.0 MTR (27)(35)(35)3)--(11)(19)<u>4.0</u>MTR Χ (36)(20)CENTER (28)(<u>36</u>) (12)4.0 MTR of(29)(37)(37)(21)ARRAY (13)4.0 MTR (<u>30</u>) (<u>38</u>) (38)(14)(22)4.0 MTR (39)(39)(15)(23)(31)

SUB ARRAY 5 & 6 SUB ARRAY 1 & 2 SUB ARRAY 3 SUB ARRAY 4 ACTIVE ACTIVE ACTIVE ACTIVE <u>Y GUN17 465 IN3 Y GUN25 465 IN3</u> Y GUN 9 465 IN3 Y GUN33 465 IN3 <u>Y GUN18 280 IN3 Y GUN26 280 IN3 Y GUN34 280 IN3</u> Y GUN10 280 IN3 Y GUN11 200 IN3 <u>Y</u> GUN<u>19</u> <u>200</u> IN3 <u>Y</u> GUN<u>27</u> <u>200</u> IN3 <u>Y</u> GUN<u>35</u> <u>200</u> IN3 Y GUN<u>12 150</u> IN3 Y GUN20 150 IN3 Y GUN28 150 IN3 Y GUN36 150 IN3 <u>Y</u> GUN29 115 IN3 <u>Y</u> GUN37 115 IN3 <u>Y</u> GUN<u>21</u> <u>115</u> IN3 Y\_ GUN13 \_ 115\_IN3 Y GUN<u>14</u> 80 IN3 <u>Y GUN22 80 IN3 Y GUN30 80 IN3</u> Y GUN38 80 IN3 Y GUN15 60 IN3 Y GUN23 60 IN3 Y GUN31 60 IN3 Y GUN39 60 IN3

### SYNTHETIC AIRGUN SIGNATURE - SETUP PARAMETERS ( FIGURE 2 )

1350 IN\*\*3 •1800 PSI \_\_\_\_\_ AUG 86

## GENERAL PHYSICAL PARAMETERS: CALCULATION PARAMETERS:

SOUND YELOCITY IN WATER DENSITY OF WATER ATMOSPHERIC PRESSURE CHARACTERISTIC MODULUS CHARACTERISTIC EXPONENT RATIO OF SPECIFIC HERTS	= = = =	63.43 14.76 2500. 8.0 1.133	ATMOSPHERE NONDIMEN. NONDIMEN.	GHOST CONTRIBUTION FLAG	= =	•	MICROSECS NONDIMEN. MICROSECS (0=NO, 1=YES) (0=NO, 1=YES) (0=NO, 1=YES)
SURFACE REFLECTION COEFF.	=	1.00	NONDIMEN.	DISPLAY SAMPLING INT.		2000	MICROSECS

### GENERAL AIRGUN PARAMETERS:

NUMBER OF GUNS IN ARRAY = 7

DAMPING COEFFICIENT =1 = 170.0 UNITS OF VISCOSITY

DAMPING COEFFICIENT \*2 = 9.0 UNITS OF VISCOSITY/SEC TYPE OF PORT CLOSURE = 2 (0=IDEAL, 1=TIME, 2=PRE (0=IDEAL, 1=TIME, 2=PRESSURE)

AIR TEMPERATURE IN GUNS = 60.0 DEGREES F

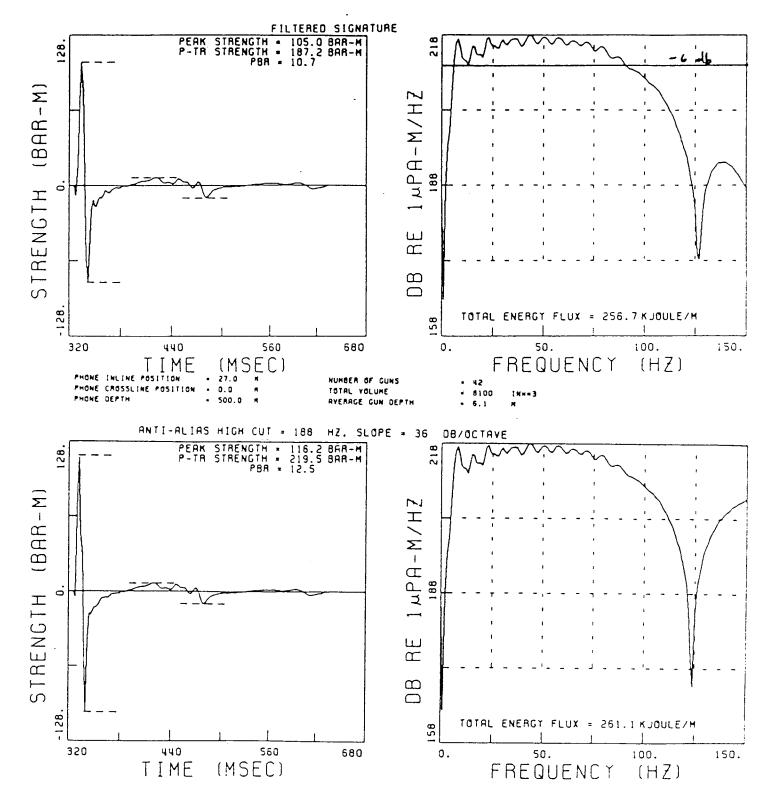
## DESCRIPTION OF AIRGUN ARRAY:

GUN =/ CONTRIB. FLAG	INLINE POSITION (FT)	CROSSLINE POSITION (FT)	GUN DEPTH (FT)	GUN VOLUME (IN××3)	INITIAL PRESSURE (PSI)	TIME DELAY (MSEC)	CLOSURE PRESSURE (PSI)	PORT AREA (IN##2)
1 / 1	0.0	0.0	20.0	465.0	1800.	0.00	150.	19.00
2 / 1	14.0	0.0	20.0	280.0	1800.	0.00	150.	19.00
3 / Y	25.0	0.0	20.0	200.0	1800.	0.00	150.	19.00
4 / Y	35.0	0.0	20.0	150.0	1800.	0.00	150.	19.00
5 / Y	45.0	0.0	20.0	115.0	1800.	0.00	150.	19.00
6 / Y	53.0	0.0	20.0	80.0	1800.	0.00	150.	6.60
7 / Y	59.0	0.0	20.0	60.0	1800.	0.00	150.	<b>6.</b> 60

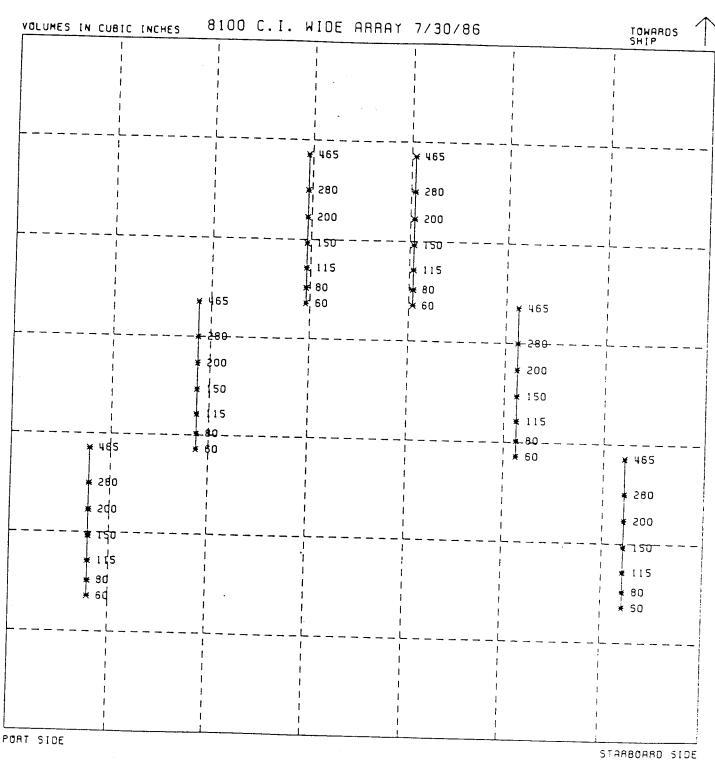
# SYNTHETIC AIRGUN SIGNATURE - HYDROPHONE NO. 1 (FIGURE 3)

FILTER DESCRIPTION:

LOW CUT . O HE SLOPE . O DE/GCTRVE HIGH CUT = 128 HZ SLOPE = 72 DB/OCTAVE



# SOURCE CONFIGURATION - PLAN VIEW (ACTIVE GUNS ONLY) ( FIGURE 4 )



1 INCH = 12 METER

#### SOURCE ARRAY RESPONSE

TOTAL LENGTH OF ARRAY:

23.77 meters

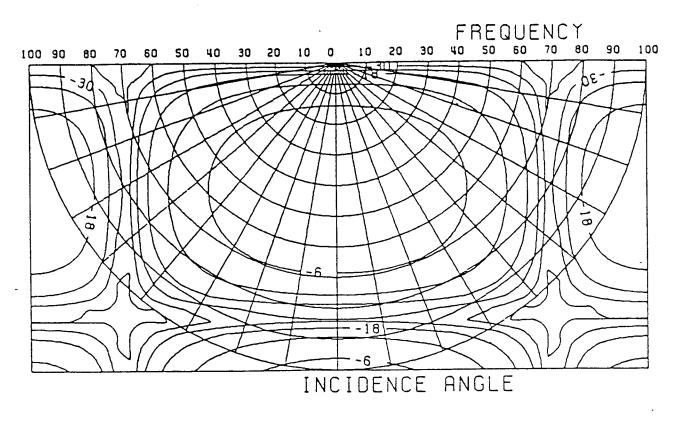
TOTAL WIDTH OF ARRAY:

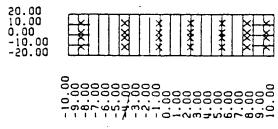
30.00 meters

NUMBER OF ELEMENTS IN ARRAY:

28

( FIGURE 5 )





Source 7.62 meters

DB contour plot of array response on a plane inclined 0 degrees to the Z-Axis and rotated 0 degrees counter clockwise from the X-Axis.

### RECEIVER ARRAY RESPONSE

TOTAL LENGTH OF ARRAY:

23.70 meters

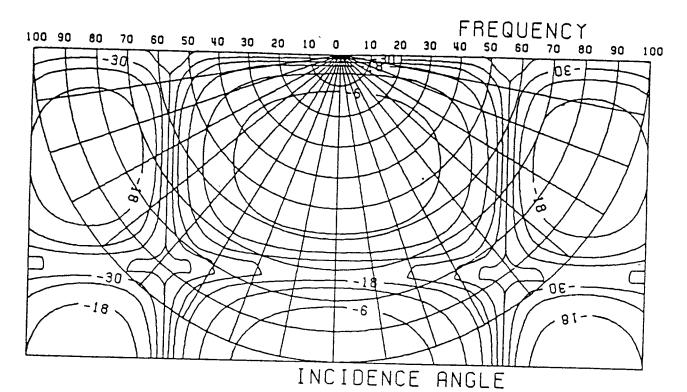
TOTAL WIDTH OF ARRAY:

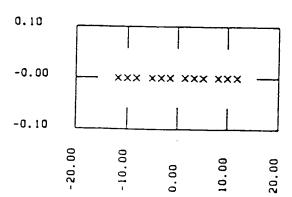
00.00 meters

NUMBER OF ELEMENTS IN ARRAY:

12

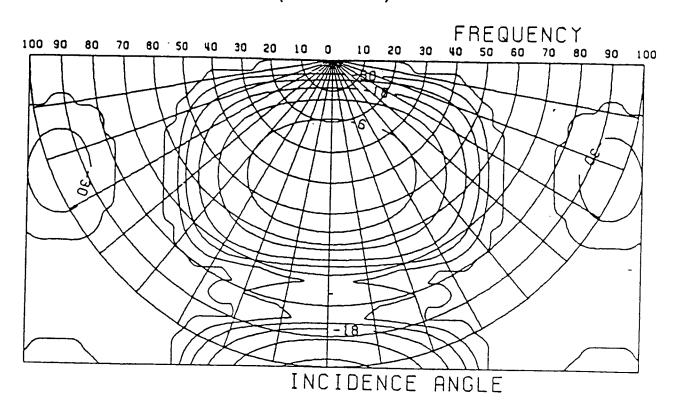
( FIGURE 6 )

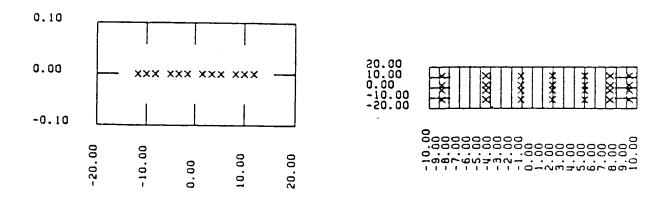




Cable 10.0 meters DB contour plot of array response on a plane inclined 0degrees to the Z-Axis and rotated 0 degrees counter clockwise from the X-Axis.

# SOURCE AND RECEIVER GEOMETRY ( FIGURE 7 )





Cable 10.0 meters - Source 7.62 meters

DB contour plot of array response on a plane inclined 0 degrees to the Z-Axis and rotated 0 degrees counter clockwise from the X-Axis.

#### CABLE CONFIGURATION

TSS\_ ROPE LENGTH 183 MTR TO TAILBUOY ----i<-B---> <u>19B</u> <u>19A</u> <u>18B</u> <u>18A</u> <u>17B</u> <u>20B</u> <u>20A</u> 17A 240 235 234 229 228 223 222 217 216 211 210 205 204 199 198 193 T C R S C R B S R S C R B S 16B 16A 15B 15A 14B 14A 13B 13A 192 187 186 181 180 175 174 169 168 163 162 157 156 151 150 145 R S C R B S R S R B S <u>12B</u> <u>12A</u> <u>11B</u> <u>11A</u> <u>10B</u> <u>10A</u> <u>9B</u> 144 139 138 133 132 127 126 121 120 115 114 109 108 103 102 <u>C</u> R S R <u>B</u> S R S <u>C</u> R <u>B</u> 8B 8A 7B 7A 6B \_5B\_ \_6A\_ \_5A\_ 96 91 90 85 84 79 78 73 72 67 66 61 60 55 54 R S R B S C R S R B <u>4A</u> <u>3B</u> <u>3A</u> <u>2B</u> <u>2A</u> <u>1B</u> <u>4B</u> 31 30 43 | 42 | 37 | 36 25 24 19 18 13 12 7 6 R <u>C</u> S R <u>B</u> S R <u>C</u> TR TO STERN OF BOAT <---->|<---->|0|= <del>----></del> <u>B</u> D <u>B</u> D D <u>N/A</u> USE LEGEND TO INDICATE LOCATION OF PERIPHERAL DEVICES CABLE CONTROLLER (B) CABLE COMPASS (C) STREAMER MODULE S COMMAND REPEATER MODULE DATA/COMMAND REPEATER MODULE D TERMINATOR MODULE O OR CONVERTOR MODULE TRILATERATION RECEIVER TR

EXAMPLE: 240 CHANNEL CONFIGURATION

M	IODUL	Æ	1	2	. 3	4	5	6	MODULE	7	8	9	10	11	12	
<	S	DT		TR		WB			R	1				1	T	S
ľ	<-					80 MTR-	-> <			80	MTR			->		
					(A)	SECTION	N	•			(B) SE	ECTION			•	

NOTE:

EACH (A) SECTION HAS A DEPTH TRANSDUCER (DT) CHANNEL AT THE HEAD.

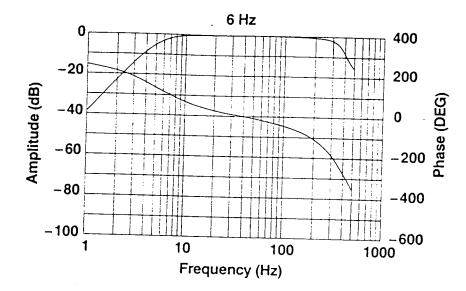
EACH (A) SECTION HAS A WATER BREAK (WB) CHANNEL AT THE CENTER OF SECTION.

# SEISMIC CHANNEL AMPLITUDE AND PHASE RESPONSE

LOWCUT FILTER:

6 Hz

( FIGURE 8 )



## PARAMETER AND EQUIPMENT REPORT

VESSEL WESTERN RESOLUTION	CREW#
CLIENT ATLANTIC GEOSCIENCE CENTER	AREA OFFSHORE NOVA SCOTIA
SURVEY DATES (INCLUSIVE) JUNE 13, 19	70 AUGUST 5, 1988
STREAMER(S):	
NO. OF CABLES USED2	MFGR LRS TYPE KILOSEIS
NO. STRETCH SECTION AT HEAD 2	NO. ACTIVE SECTION ON CABLE 40 EACH
ACTIVE CABLE LENGTH 3200 MTR	CABLE DEPTH 9.14 MTR
NO. RAW GROUPS/CABLE 240	DODM / AMD D
NO. PHONES/RAW GROUP 6	NEAR GROUP NO. 1 / 241
TYPE HYDROPHONES LRS 2510	PHONE SENSITIVITY (UV/UBAR) 27.0
NO. DEPTH CONTROLLERS/CABLE 17 EACH	TYPE SYNTRON
<u>270</u> <u>293</u> ; <u>294</u>	30; 53; 54; 77 78; 101; 102; 125 126; 144; 767 197; 198 221; 222 245 246 269; 317; 318 341; 342;;;
NO. COMPASSES/CABLE 14 EACH	TYPE SYNTRAK
<u>347</u> <u>348</u> ; <u>359</u>	18; 41       42; 71       72; 107       108; 143       144;         204; 227       228; 263       264; 299       300; 323       324;         360;;;;;;;;
NO. DEPTH DETECTORS/CABLE 30 EACH	TYPE <u>HPDT-207-1</u> (SEE CABLE CONFIGURATON PG.
NO. WATER BREAK DETECTORS/CABLE 4 EA	TYPE WMH-036 FOR LOCATIONS)
SPECIAL INSTRUCTIONS:	

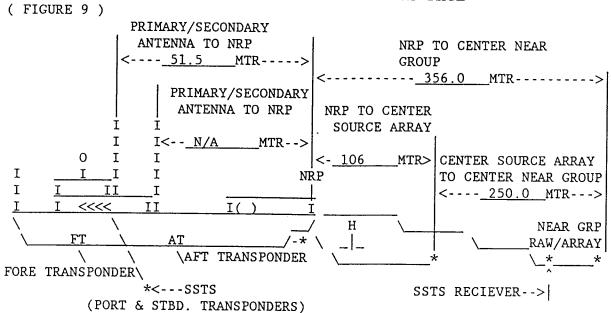
### INSTRUMENTS

FATHOMETER:	MFGR SIMRAD MODEL AR-805 PRINT IN (FT, FATH, MTR) MTR
SINGLE TRACE PROFILER:	NO.USED 2 MFGR RAYTHEON MODEL 1800 ARRAY GROUP RECORDED/CABLE 3 /243
RECORDING SYSTEM:	MFGR LRS MODEL LRS 16A S/N #4
RECORDING PARAMETERS:	
SEG FORMAT/CODE "	RAW ARRAY ECORDED 24 SEC/4 MILL  " 6250 BPI AT 125 IPS  " SEG-D / 8024  " TELEX 6253  " 180/4  " YES
USER HEADER FORMAT HE-10089 (384 BYTE	SS)
ARRAY PROM CODE <u>43</u> = <u>180</u>	-
ARRAY LENGTH = 2 RAW GRPS	
ARRAY WEIGHTING <u>0.5</u> , <u>0.5</u> , <u>0</u> , <u>0</u>	,OVERLAP50%
FILTERS:  RAW: HI CUT N/R HZ N/R DB/O  ARRAY: HI CUT 87 HZ 132 DB/O	CT - LO CUT <u>N/R</u> HZ <u>N/R</u> DB/OCT CT - LO CUT <u>6</u> HZ <u>24</u> DB/OCT
WGC QC PLOT SYS (Y/N) Y	PLOT INTV 40 SP
OTHER FUNCTIONS	POLARITY (QC & CAMERA) BREAKS DOWN
TAP BREAKS (UP/DN) <u>DOWN</u>	SCRIBE TAPE (UP/DN)
NO. STREAMER MODULES/CABLE 20 EACH	NO. REPEATER MODULES/CABLE 20 EACH
NO. DATA/COMMAND REPEATERS/CABLE <u>2_EAG</u>	
TELEMETRY ERROR CORRECTION (Y/N):SPIK	E <u>Y</u> TIME BREAK VOL OR FIX <u>VOL</u>
AUX CH. ASSIGNMENTS: 1_GUNS 25,28,31	NO. AUX CHANNELS

## NAVIGATION

PRIMARY: TYPE LORAN	MFGR/CONTRACTOR DIGITAL MARINE / WGC
SECONDARY: TYPE	MFGR/CONTRACTOR
NAV SPHEROIDCLARKE 1866	DATUM SHIFTNAD (27)
STREAMER LOCATION:	COMPASSES IN USE (Y/N) Y
	TRILATERATION IN USE (Y/N) Y
	TYPE SSTS
NAVIGATION REFERENCE POINT (NRP):	
	BACK DECK ROLLER AT STERN.
GRAVITY: N/A	
MFGR	MODELS/N
DISTANCE FROM SENSOR TO BOW	
SPECIAL INSTRUCTIONS N/A	
MAGNETOMETER: N/A	
MFGR	MODELS/N
DISTANCE FROM NRP TO MASTER SENSOR	
DISTANCE FROM NRP TO SLAVE SENSOR _	MTR
SPECIAL INSTRUCTIONS N/A	

#### NAVIGATION REFERENCE PAGE



#### REFERENCE OFFSETS:

LOCATE IN RELATION TO	ABOVE (+	·)	FORE (+)	)	STARBOARD	(+)
NAVIGATION REFERENCE POINT:	BELOW (-	)	AFT (-)	)	PORT	(-)
CENTER GUN ARRAY	36ft +/- 3	ft+H	-106.0	MTR	0	MTR
CENTER NEAR GRP RAW *	N/A	MTR	N/A	MTR	N/A	MTR
CENTER NEAR GRP ARRAY*	45ft +/-6f	t +H	-356	MTR	0	MTR
SATELLITE ANTENNA	+16.85	MTR	+51.97	MTR	-0.0	MTR
PRIMARY ANTENNA	+13.53	MTR	+51.47	MTR	-0.76	MTR
TYPE:LORAN C				l		
SECONDARY ANTENNA		MTR		MTR		MTR
TYPE:						
TRILATERATION (SSTS) COMPONE	HTS					
FORE HULL TRANSDUCER	-12.4	MTR	47.87	MTR	+.049	MTR
AFT HULL TRANSDUCER	-12.4	MTR	19.00	MTR	04	MTR
STBD TRANSPONDER	-16.0	MTR	35	MTR	25	MTR
PORT TRANSPONDER	-16.0	MTR	35	MTR	-25	MTR
FATHOMETER TRANSDUCER	-12.4	MTR	+49.0	MTR	04	MTR
WATER LINE		MTR	****	MTR		MTR

#### \* INCLUDING STRETCH

NOTE: REFERENCE TO NEAR GROUP OFFSET WILL VARY SLIGHTLY. OFFSETS SUPPLIED ABOVE ARE USED AS DEFAULT VALUES WHEN TRILAT IS IN USE.

The following navigation equipment were utilized during the survey:

-WISDOM® (Western's Intergrated Survey Data Onboad Management) navigation computer system;

-Loran C

## **GEODETIC PARAMETERS:**

Spheroid Code	2		
Spheroid Name	CLARKE (	1866)	
Semimajor Axis	6378206.		Meters
Flattening	0.003390	0753	
Local Datum	NAD-27		
Delta-X	41.000	Meters	
Delta-Y	-147.00	Meters	
Delta-Z	-181.00		
False Northing	0.0		
False Easting	500000.0		



## M/V WESTERN RESOLUTION (P-115)

Name:
Owner:

M/V Western Resolution Western Sea Services, Inc.

Flag:

Panama

Construction:

1982, Batservice Verft A/S, Mandel,

Norway

Official Registration:

13129-NO

Call Sign:

HP-4602

Dimensions:

Length: 75.20 meters (246.70 ft.)
Breadth: 15.60 meters (51.25 ft.)
Draft: 5.90 meters (19.30 ft.)

Net Tonnage: 147.00 Gross Tonnage: 1437.00

Speed:

13.00 knots cruisisng (clean bottom)

Fuel Capacity:

160,000 gallons

Fuel Endurance:

50 days (estimated running full

speed)

Potable Water Capacity:

54,000 gal

Water Endurance:

Estimate 14 days (indefinite using

watermaker)

Main Engine:

4 Bergen Diesel (9 cylinder)

Diesel Electric:

4 x 1550 BHP @ 720 RPM 3200 shaft

horsepower

Electric Propulsion:

4 ASEA DC motor 600 kw, 720V, 880A

Propeller:

1 Hjelset-Controllable Pitch (9.7')

Main Generators:

4 ASEA 1450 Kva 1395 A 600V 60.0 Hz.

Emergency Generator:

Engine: Cummins 6 cylinder

Gen.: Stamford 312.5 KVA 440V 410A

60.Hz.

Bow Thruster:

1 600 H.P.

Incinerator: Yes

Sewage Treatment System: Yes

Gyro:

Auto Pilot: Sperry Gyropilot

RADIOS:

Radios-1 x Icom (SSB) 150 watt

1 x Skanti (SSB) 750 watt 1 x Sailor RT-146 VHF

1 x Ratheon 66 VHF 1 x Dancom RT 408 VHF

1 x Simrad RW 105 Watchstander

Voice/Telex -Alden Marinefax

Cellular Phone -OKI 201 fitted with data

RADAR:

Wheelhouse -2 Sperry MK 4016 w/ Cas II

2 Sperry MK 227

Weather Fax: Alden Marinefax

Fire Fighting Equip.: Halon 1301, AFFF foam

Fire Monitors

#### GEOPHYSICAL EQUIPMENT

#### RECORDING INSTRUMENTS:

LRS-16A, 480 channel with 4 auxillary traces LRS-100, 64-Gun Synchronizer System

Raw Format: Not Recorded

Array Format: SEG-D

Number of Aux. Channels: 4
Time Break Channel: 1

Low-cut Filters: 6 Hz - 24 DB/OCT

Header Expander System: MLHEU 8.8

Airgun Simulator Test Unit: YES

ESM System: YES

Line Scan Recorder: Raytheon 1800

Compass System: Syntron Model RCU-831

#### CABLE INFORMATION:

2 each LRS-16 KILOSEIS

240 raw channels, 120 array, 3200 meters

40, 80-meter sections

Raw Grup Interval: 13.333 meters Array Group Interval: 26.67 meters

Depth Indicators: 20 LRS-16 internal Depth Controllers: 12 Syntron RCL-3

individual remote control

Hydrophones: WM2-036

Number Phones/Groups:

Crystal Capacitance: .036UF %5

#### ENERGY SOURCE INFORMATION:

42 Bolt Low Pressure 40 ci" thru 485 ci"

Compressors: Burkhardt:

2 Model B55 1400 SCFM 2 Model B5Q 750 SCFM

Distance Between Guns: Operating Pressure:

4 meters 1800 psi

Dual Arrays:

no

Gun Depths at Normal Operation: Type of Phones Used for Gun Break: WMH-036

25 feet

#### NAVIGATION:

WISDOM® Version "E" with RESCU Box, Status Closure Panel

Satellite Receiver:

Magnavox MX1107-RS

Loran C:

Northstar 6000

3D-QC Package: Gravity Meter: Magnetometer: Doppler Sonar:

yes no no no

SSTS:

yes

#### G. LRS-16A TECHNICAL SPECIFICATIONS:

The following specifications are written based on use of the LRS-16A Shipboard Electronics Upgrade with standard LRS-16 cable sections and modules. In addition, the specifications include the assumption that the 125 ips, 6250 bpi Telex Tape systems for both raw and array data recording will be used.

#### General:

The LRS-16A is a microprocessor-based shipboard electronics enhancement to the existing LRS-16 system. It utilizes the Motorola 68000 microprocessor, the VMEbus standard, and Eurocard packing techniques. It is designed to easily incorporate future expansion as the LRS-16 seismic acquisition technology continues to develop. The system is designed to handle 480 seismic input channels at a 1-msec sample interval and process the data using the IEEE, 32-bit floating point format; this was done in order to work with future expansions in the area of higher resolution A/D converters.

### Cable Configurations Support:

The system will service and acquire data in any increments of the following:

80 mts, 12 channel sections (480 channels, 3200 mts. max.) 160 mts, 12 channel sections (360 channels, 4800 mts. max.) 160 mts, 8 channel sections (240 channels, 4800 mts. max.)

#### NOTE:

Extension of the cable to 4800 meters and 360 channels (160 meter increments) requires a minor change in the delay line tap in the streamer modules. The modified modules cannot then be used in the 480 meter configuration for a single cable.

# Raw Data Processor and Recording

Cable Sampling Interval:

1 msec

Recording Format:

SEG-D Multiplexed format 2-byte, hexadecimal format Code 0040 (sign and magnitude) gapped data

Bytes per scan -

Depends on number of channels

Scans per block -

Depends on number of channels (bytes

per block 65K)

Header size -

288 bytes + user header

Recording Sample Rates:

1-, 2-, or 4-msec

Anti-alias Filters -

1 msec.

-3 db @ 350 Hz 72 db/oct Module Analog approximates an Inverse Chebyshev

2 msec.

-3 db @ 188 Hz 156 db/oct Digital FIR (zero

phase)

4 msec.

-3 db @ 87 Hz 132 db/oct Digital FIR (zero phase)

Low-Cut Filter:

-3 db @ 6 or 12 Hz @ 24 db/oct (includes module low-cut)

Waterbreak Channels -

Number Recorded Anti-alias Filter Low-Cut Filter Recorded Sample Rate

4 nearest the vessel None Same as seismic channels Always 1 msec

## Shipboard Auxiliary Channels:

Number Recorded	4 (from Cable Interface Electronics (CIE))
Filtering	Same as seismic channels except for auxiliary channel 4
Sampling Skew:	Module sampling skew-corrected using digital interpolation filter
Error Detection:	Errors are detected using an adaptive cubic polynomial function plus threshold window.
Error Correction:	Errors are corrected using predicted value if sample is determined to reside outside of acceptable limits.
Maximum Record Lengths.	240 Goimmi

Maximum Record Lengths:	240 Seismic	480 Seismic
1 msec	20	17
2 msec	20	20
4 msec	20	20

NOTE: These figures will change depending on the cable configuration, i.e., number of channels being recorded.

Playback:	Read-after-write data is processed and output to a galvo camera and seismic QC system for evaluation.
Seismic Channels - (Galvo Camera)	Up to 48 channels selected by the operator can be displayed in AGC or fixed-gain, 6 db steps.
Seismic Channels - (Seismic QC System)	All channels plotted simultaneously with operator-selectable programmed gains.
Auxiliary Channels - (Galvo Camera)	4 channels, fixed-gain, 6 db steps.

## Array Data Processor and Recording

(Galvo Camera)

Input Data to Array Data Processor:

Data is input from the Raw Data Processor after having been

processed through the following: Data Mapping, Error Detection and Correction, Skew Correction, and Low-Cut Filtering.

Number of Input Data

Channels:

960 (maximum)

Recording Format:

SEG-D Demultiplexed format, 2-byte, quaternary format Code 8024 (1's

complement)

Header Size:

Depends on number of array output channels, number of coefficients, type of process, Beam Steering, time

variant, etc.

Recording Sample Rates:

1-, 2-, or 4-msec.

Anti-Alias Filters:

1 msec.

-3 db @ 375 Hz 156 db/oct

Digital FIR (zero

phase)

2 msec.

-3 db @ 188 Hz

156 db/oct

Digital FIR (zero

phase)

4 msec.

-3 db @ 87 Hz

132 db/oct

Digital FIR (zero

phase)

Auxiliary Channels:

Number Recorded -

4 (from CIE)

Filtering -

Same as seismic channels except for

auxiliary channel 4

Gun Phone Channels:

Number Recorded -

Up to 64

Record Length -

Maximum of 512 samples

Filtering -

Low-Cut performed in Gun Monitor Unit; -3 db @ 6 Hz, 18 db/oct.

Anti-alias filtering performed using the same digital filter as selected for the Array Seismic Channels.

Number of Array Output

Channels:

240 (maximum), 1 (minimum)

Maximum Length of Arrays:

16 @ 240 output channels 32 @ 120 output channels

Array Overlapping:

Up to 8 arrays may reference the same inout channel; can be more depending on configuration.

Array Definition:

Up to 4 configurations processed concurrently.

Maximum of 4 coefficients sets per

configuration.

Maximum of 32 coefficients per set.

Dynamic Correction:

Partial NMO correction performed on raw data channels used to form the output Array Channel.

Maximum Correctable Delay:

63 msec.

Time Variant Weighting:

Up to 3 times windows per record within which the coefficients are computed by linear interpolation.

Maximum Record Lengths	Overlapped (Seconds)	Non-Overlapped (Seconds)
1 msec	6	12
2 msec	12	24
4 msec	24	1 Q

NOTE:

These times are for a maximum of 240 channels and will be larger for fewer channels. Overlapped record indicates that another record can be started while the previous one is still being recorded on tape.

Playback:

Read-after-write data is processed and output to the seismic QC system for evaluation.

Seismic Channels - (D/A Scope Display)

Up to 60 channels selected by the operator can be displayed in AGC or fixed gain, 6 db steps.

Seismic Channels - (Seismic QC system)

All channels plotted simultaneously with operator-selectable programmed gains.

Auxiliary Channels - (D/A Scope Display)

4 channels, fixed-gain, 6 db steps.

# LRS-16A SYSTEM 240-CHANNEL STREAMER CABLES

 The active portion of the LRS-16 streamer cable consists of several types of cable sections and modules:

## Cable Sections

- 1. Stretch
- 2. Active
- 3. Tail

SSTS section zero module adapter with cross cable pingers.

## Modules

- 1. Streamer
- Command Repeater
- Data/Command Repeater
- Terminator

The active streamer sections are tied in directly behind the electronic modules and are 80 meters long measured center-to-center of the modules. Hydrophone groups are spaced evenly over the entire section length. Each section contains a water-break (signature) phone located in the center, a depth transducer toward the front, and an optional compass unit toward the rear. Each cable consists of 40 active cable sections and 20 streamer modules, each with 12 seismic data channels. Channels 1 to 6 represent hydrophone groups located directly downstream from the streamer module. Behind group 6 is a command repeater module that is used to buffer commands from the shipboard electronics to the next streamer module downstream.

The Command Repeater Module also connects hydrophone channels 7 to 12, located directly downstream, to the streamer module upstream. This allows all active cable sections to be interchanged. Streamer modules in the cable are 160 meters apart.

The command repeater modules are located at the 80 meter point midway between two streamer modules. The streamer and command repeater modules are numbered 1 through 20 in stb cable, with number 1 module closest to the vessel and 21-40 in port cable, with number 21 closest to vessel. A data/command repeater module is located as a lead-in module between the lead-in and stretch sections. The data/command repeater module buffers signals over the extended distance between the shipboard electronics and streamer module 1.

# Active Sections

Each of the 40 identical active sections is 80 meters long. Each section is located between a streamer and a command repeater module. Each active section contains 36 hydrophones in a configuration of 6 groups of 6 parallel connected phones. Each section contains a depth transducer between the electronics module and the first hydrophone, and a water-break detector at the 40 meter location between hydrophones 18 and 19.

Locations for compass units and depth controllers are between hydrophones 30 and 31, 33 and 34, respectively. These locations are marked with blue spacers for easy identification and monitoring of the external devices.

The tail end of each active section terminates in a Viking connector for attaching the next module downstream. All active sections are filled with oil and balanced for buoyancy. Each section contains the basis complement of wires plus 16 additional pairs.

# 3. Tail Section

A terminator module connected behind the last active section provides signal line terminations. The tail section is 80 meters long and connects to the tail end of the terminator module via a Viking connector. The aft end of the tail section is connected to a tail swivel which attaches the towing rope for the tail buoy. The tail section, like the active sections, is oil-filled and balanced for buoyancy. The only wires running through the tail section are the two 26-gauge twisted-pair depth controller lines, which are terminated in open sea at the tail swivel for a seawater ground return to the control module on-board the recording vessel.

# 4. Active Section Elements

# a) Hydrophones

Thirty-six LRS-2510 series hydrophones, Model WM2-036, are used in each active section of the streamer cable, parallel connected in 6 groups of 6. The hydrophone is a pressure-sensitive device with a sensitivity of 27 volts/bar + 5%, a maximum recommended working depth of 60 meters, and dimensions of 58 x 23 x 31 mm.

### b) Water-break Detector

One LRS-2510 series hydrophone, model WMH-036, is installed in each active section for use as a water-break detector. This single hydrophone, located at the center of the cable section, detects the very high frequency direct arrivals from the energy source. The water-break hydrophone is not used in sections aft of a command repeater module.

# c) Depth Transducer

An open sea type depth transducer is installed on each active cable section approximately 1 meter behind the electronic module. The depth transducer is a two-element amplitude modulation device which receives a 500 Hz square wave signal from the module for transducer power.

The square wave is converted to a sine wave for returning an amplitude-modulated signal to the module amplifier. The depth transducer is not used in sections aft of a command repeater module.

# d) Depth Controller

Toward the tail end of each active section, an isolation point is provided for attaching a Syntron Depth Controller. The approximately 2 meter long isolation point, which has an oil block at each end, is located approximately 6 meters from the aft end of the cable section. Five blue spacers are used to identify the isolation point. The basic wire complement of the LRS-16 cable sections include two spare lines of 26-gauge twisted-pair wire for use with depth control devices. RCL 2's and RCL 3's are used.

The lines run through the terminator module and tail section to the tail swivel for seawater (ground) return.

## e) Compass

Each active cable section contains an isolation portion for use with a Syntron exterior-mounted compass unit. Approximately 12 meters from the tail end of the section, three 3 meter long stainless steel wire ropes are spliced in to replace the three galvanized wire rope stress members. Oil blocks also are used for isolation fore and aft of the compass location. The basic wire complement of the LRS-16 cable sections contained two 22-gauge compass lines, one for an interior compass and one for an exterior-mounted compass.

#### 5. <u>LRS-16 Modules</u>

a) Each electronic streamer module is a data acquisition system operating remotely at the hydrophone input. Each module contains the circuitry required to amplify, sample, gain, digitize, and telemeter local data, as well as the circuitry for repeating downstream data. Other major circuits include command decode, bypass control, and test and power. Hybrid circuits are used extensively because of their reduced size and weight and their high performed.

Transformer coupling for the hydrophone inputs are eliminated by using a charge-couple amplifier for each channel. This is a current-type device that directly connects to the hydrophone by wire and provides excellent signal-to-noise ratio.

Incoming local data are filtered, pre-amplified, anti-aliased, and output to the instantaneous gain-ranging circuitry. High speed (12 bits in 12 microseconds) analog-to-digital conversion is performed and the di-phase encoded data are output to the data line via an output transformer. Emmiter-coupled logic (ECL) is used to drive the signals in current mode at very high speed.

The module is controlled by synchronization (SYNC) and interrogation pulses (IP) from the shipboard electronics. A patented system of polling the modules eliminates the need for any special module addressing and means that each streamer module is identical and interchangeable.

During a seismic record, 1 SYNC and 14 IP's are transmitted every millisecond to the 15 channels of each module. A 20-bit burst of data is transmitted from the module for each sample of each channel, an artificial delay being used to separate the data burst from module to module. The streamer module has 15 available channels.

# CHANNEL NUMBER O Quality Control Water-break 2 - 13 Seismic Data 14 Depth Transducer

In addition to the SYNC/IP line, there are two command lines for module control. Command A is for IP blocking and Command B is for bypass. Bypass control can be used for troubleshooting purposes and for disabling a malfunctioning module. Module bypass is accomplished electromechanically by commanding module n-1 to turn off module n.

A test circuit in the streamer module receives a 31.25 Hz precision signal from the shipboard electronics and outputs the signal to the hydrophones for accurate calibration. In the test mode, the calibrate signal is recorded on tape in place of the water-break signal.

A 2 KHz signal, synchronous to the shipboard electronics master sampling oscillator, is used for module power. The 2 KHz signal is outside of the pass band and allows for small current transformer to be series connected in each module.

# b) Command Repeater Module

Command repeater modules, which are used alternately with streamer modules, connect two active cable sections and allow each of the 40 sections to be built identically. The main function of the command repeater module is to buffer commands from the streamer module upstream to the next streamer module downstream. Deterioration of the SYNC and IP is prevented by maintaining accurate pulse widths.

Downstream seismic channels 1 through 6 are wired in the command repeater module to become channels 7 through 12 in the streamer module upstream. Physical construction of the command repeater module is identical to that of the streamer module, except that the only one active PC board is used; two are blank.

# 6. Cable Depth Monitor (CDM)

The CDM provides two main display functions:

- a) A profile depth display of all active cable sections, relative to sea level.
- b) A raw hydrophone group channel display; the video image includes all seismic channels (480); the operator can scan for a selected cable section to observe the 12 seismic channels of a particular module.

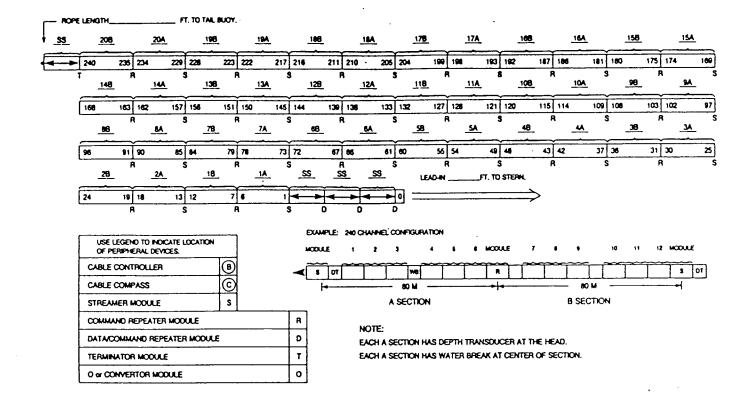
The CDM also performs depth transducer calibration for the cable depth display.

The depth output board interfaces with external equipment and provides a depth data output in BCD byte format: 1 byte (per module) contains two 4-bit BCD digits representing cable depth in feet. This information can be included in the external header and fed back into the LRS-16 via the RDP (raw data) and DMM (array data) for recording on tape. The depth output board also outputs composite video data for a remote CRT.

# 7. <u>Seismic Quality Control</u> (SQC)

The SQC contains a file memory, arithmetic unit, and microcomputer control. Read-after-write data from the RFT and ATF are input to the SQC for verification. The seismic record is analyzed for noise and data quality. At intervals of approximately 10 shots, the SQC output is displayed on a plotter.

# STREAMER CONFIGURATION (FIGURE 10)

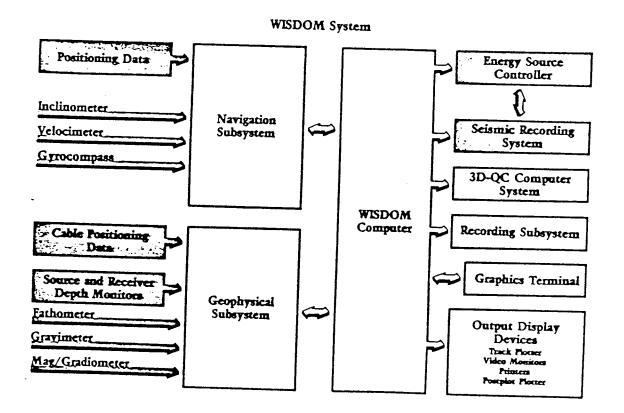


# H. WESTERN INTEGRATED SURVEY DATA ONBOARD MANAGEMENT (WISDOM®)

# 1. General

The standard WISDOM® System is a computer-based system integrated with an interface (GDU) to which a variety of auxiliary navigation sensors can be connected. The system consists of an HP2117F computer (CPU), an HP2649C Operator Terminal with Graphics Display, a 9-track 800 BPI Tape Deck and a Line Printer. The system integrates a Magnavox MX1107 Dual Channel Satellite Receiver, a Magnavox MX610 Doppler Sonar, and High Precision Radio Positioning. The WISDOM® System computes precise firing locations for the energy source in either distances-along-the-line or velocity-based time intervals. It records all non-seismic data and displays continuously a summary of navigation data.

( FIGURE 11 )



# 2. The Satellite Sub-System

A Magnavox MX1107 Dual Channel Satellite Navigator provides continuous real time satellite navigation from the Navy Navigation Satellite System (NNSS). The receiver passes raw satellite data to the central processor (HP2117F) for reduction by the WISDOM® operating system. The Magnavox receiver also provides a stand-alone fix computation as well as satellite pass predictions.

# 3. The Geoscience Data Unit Sub-System (GDU)

The GDU maintains synchronous data ports for all non-seismic data such as gravity, magnetics, depth, streamer heading sensors and depths, gun depths, gun synchronization information, tail buoy data, and all radio navigation data. The GDU also outputs closures for gravity and magnetic event markers, and reformats data for the seismic system. All data which is channelled through the GDU passes to the WISDOM® System for recording on the WISDOM® tape.

# 4. Radio Navigation Sub-Systems

Radio navigation sub-systems give radio ranges to the GDU and to the WISDOM®. The WISDOM® accepts as many as 16 radio patterns from available positioning systems. Signal conditioning for the raw patterns includes spike editing, filtering, and static corrections.

All 16 radio patterns are recorded at two-second intervals and at each pop. Filtered values are recorded at ten-second intervals as well as at each pop.

Up to 6 independent solutions can be selected from any two through six of the 16 possible input radio patterns. These solutions can be geodetically absolute or the data can be used for velocity sensing between satellite fixes. Each absolute solution is based on the various range data and their standard deviations. Thus, relatively noisy data are suppressed. The solution is accompanied by a quality-of-solution parameter for the multi-range data. For radio positioning geodetic quality control, the operator can confirm geodetic parameters against pre-plots through static checks.

Vessel position, course, and later deviation of the vessel from pre-plot track are continuously displayed on video

units located both on the vessel's bridge and in the navigation recording room. Quality control data such as base stations intersect angle, multi-solution fix-error, cable attitude, post line histograms displaying cross course deviation, shotpoint spacing and residual of fix resolutions are displayed on the operator's graphics terminal.

A permanent printed log is provide through a Diablo printer. All data are recorded on magnetic tape through a Pertec tape transport.

These types of radio positioning systems' outputs, range, phase and time, can be interfaced to the WISDOM® system. Range types include Shoran, Syledis, Maxiran, Trisponder, Del North, Microphase, and Miniranger. Phase (lane) types, circular or hyperbolic, include Argo, Lorac, Raydist, and Hi-fix. Time types include Accufix (Loran-C), Pulse/8, and Toran.

### I. TESTS AND CALIBRATION

Prior to the start of the survey, a semi-monthly instrument test is performed on the LRS-16 recording system. Test data is analyzed by field systems QC of Western Research. In addition, daily system tests were run through the survey to insure seismic instrument integrity. Also a series of diagnostics were performed on all remaining shipboard systems.

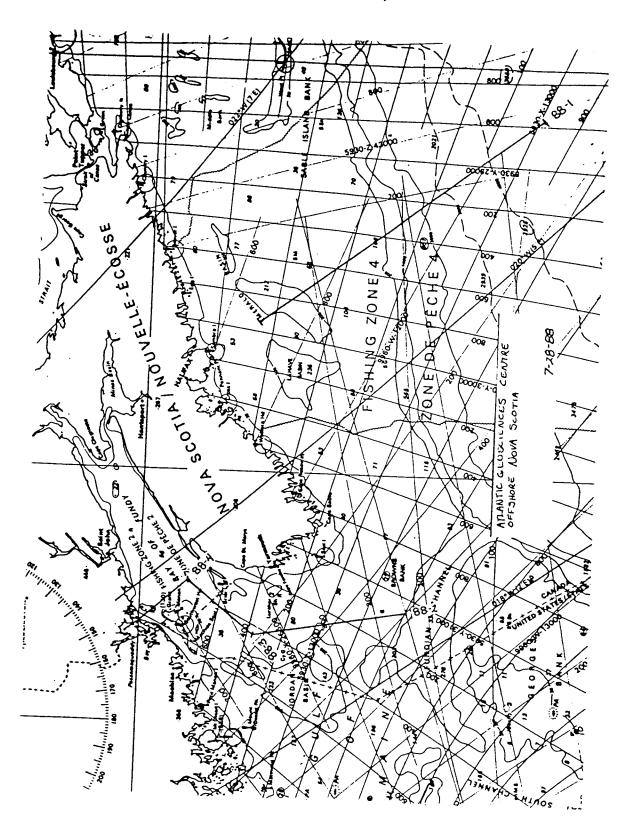
# I. SURVEY PARAMETERS AND LINE INFORMATION

1. Definition of Survey Lines :

LINE	SHOT POINTS FSP LSP	INITIAL POSITION NORTHING EASTING	FINAL POSITION NORTHING EASTING
88-1	100 4441	41 34 0.00 -60 37 0.00	NORTHING EASTING  44 4 0.34 -63 10 0.36
88-2	100 1982	42 40 0.00 -66 40 0.00	43 59 59.46 -66 59 59.86
88-3	100 1148	44 0 0.00 -67 0 0.00	44 34 59.49 -66 20 0.59
88-4	100 894	44 35 0.00 -66 20 0.00	44 59 59.36 -66 52 59.15
88-4	100 1093	44 59 59.36 -66 52 59.15	45 7 0.03 -67 0 0.03

Grid Projection: Transverse Mercator Origin Latitude: 0.0° Origin Longitude: 0.0° False Northing: 0.0 meters False Easting: 500000.0 meters Scale Factor: .9996 Spheroid Name: Clarke (1866) Semi-Major Axis: 6378206.4 meters Flattening: 0.003300753 meters Local Datum: NAD 27 X Shift: 41.0 meters Y Shift: -147.0 meters Z Shift: -181.0 meters

AREA SURVEY MAP ( FIGURE 12 )



### K. SUMMARY

The survey was completed on August 31, 1988 to a total of 583.2177 kilometers of 30 fold seismic data with both seismic and navigation data being shipped to Western's Calgary office for processing.

Despite the slow commencement due to the generator failure, the survey progressed fairly smoothly once under way. Weather was not a factor in delays, but the naturally strong currents in parts of the prospect area did create noise and high feathering angles which were grounds for standing by and re-shooting. Also, fishing activity caused some delays in production.

Close to all of the pre-plotted seismic line was shot despite the acquisition obstacles and this was done staying within the client's budget.